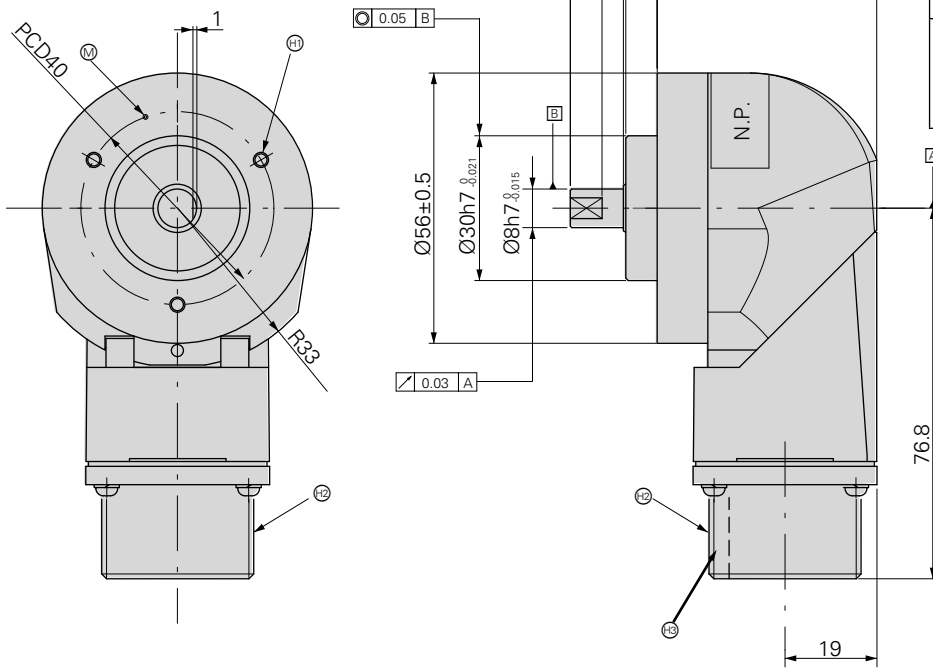
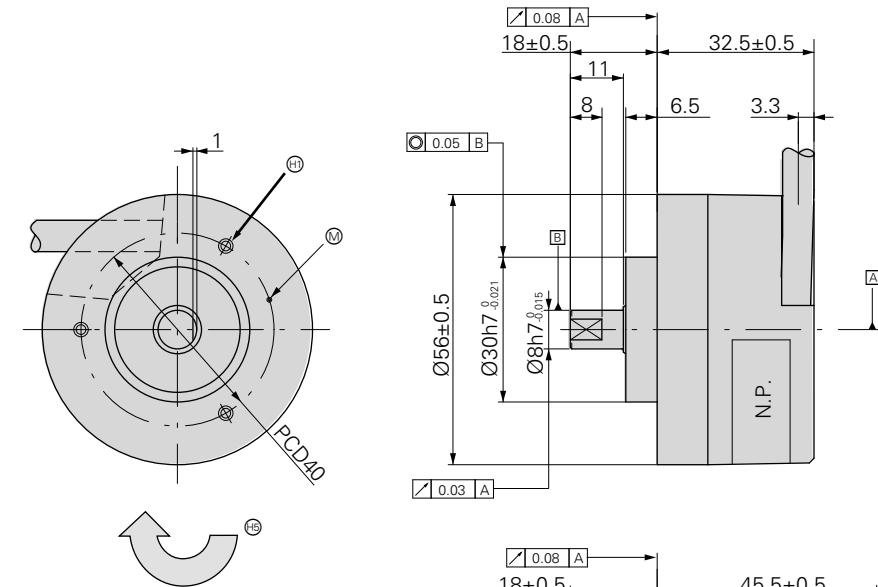


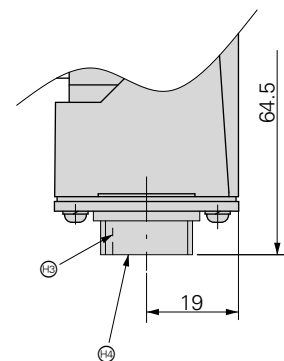
ROD 400 Series

Incremental Rotary Encoders for separate rotor coupling

- Outer Diameter 56 mm
- Length 32.5 mm/45.5 mm
- Shaft Diameter 8.0 mm



Flange socket	Mating connector
10-pin RM15WTRZ-10P(71)	Connector RM15WTRZ-10S(71) Clamp JR13WCC-10(72)
17-pin MS3102E20-29P	Connector MS3106B-20-29S Clamp MS3057-12A






Dimensions in mm



Tolerancing ISO 8015

- (M) = Measuring point for operating temperature
- (H) = 3-M3, Depth 6, Equally Spaced
- (F) = Flange socket MS3102E20-29P(Equivalent)
- (K) = Key
- (R) = Flange socket RM15WTRZ-10P(71)
- (S) = Direction of shaft rotation for output signals as per the interface description

	ROD 420	ROD 430	
Incremental signals	 TTL - C ¹⁾	 HTL - C ¹⁾	 HTLs ²⁾ - C ¹⁾
Output pulse * (Accuracy Class)	100 ^(l) 200 ^(l) 300 ^(l) 500 ^(l) 512 ^(l) 600^(l) 900 ^(l) 1000 ^(l) 1024^(l) 1200 ^(l) 2500 ^(l) 4096 ^(l) 5000 ^(l) 10000 ^(ll)		
Scanning frequency Edge separation <i>a</i>	≤ 300 kHz ≥ 0.41 μs	≤ 200 kHz ≥ 0.62 μs	
System accuracy	Accuracy Class I : ±1/10 SP Accuracy Class II : ±1/5 SP		
Power supply Current consumption without load	5V ± 10% ≤ 70 mA	10.8V to 26.4V ≤ 70 mA	
Output current	± 10 mA	± 20 mA	≤ 40 mA
Electrical connection	<ul style="list-style-type: none"> • Cable 1m, without connector • 17-pin MS3102E-20-29P flange socket, radial • 10-pin RM15WTRZ-10P(71) flange socket, radial 		
Shaft	Solid shaft D = 8 mm		
Mech. permissible speed n	≤ 6000 min ⁻¹		
Starting torque (at 20°C)	≤ 0.007 Nm		
Moment of inertia of rotor	3.0 · 10 ⁻⁶ kgm ²		
Shaft load	Axial : 20 N Radial: 30 N		
Vibration 25 to 2000 Hz Shock 6 ms	≤ 100 m/s ² (JIS C 60 068-2-6, EN 60 068-2-6) ≤ 1000 m/s ² (JIS C 60 068-2-27, EN 60 068-2-27)		
Max. operating temp. (Ambient Temperature)	90°C (85°C)		
Min. operating temp.	For rigid configuration : -20°C For frequent flexing : -10°C		
Protection EN 60 529	IP64 (IP66 when shaft is stationary)		
Weight	Approx. 0.2 kg (without cables)		

Bold : preferred versions

* Please select when ordering.

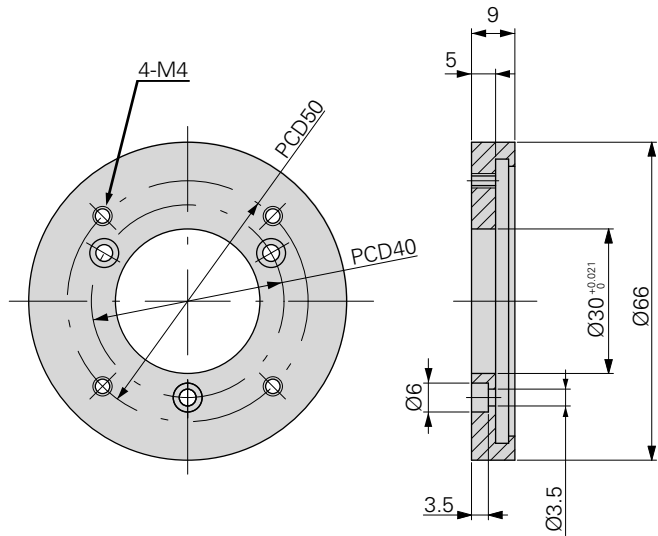
¹⁾ Bypass capacitor is connected to FG.

²⁾ Without inverse signal

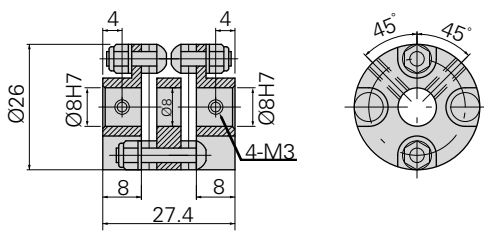
Mounting Accessories



Mounting flange for ROD 400 series
ID 728 586-01



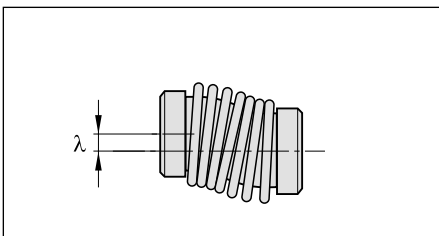
Rotor coupling for ROD 400 series
ID 731 375-01



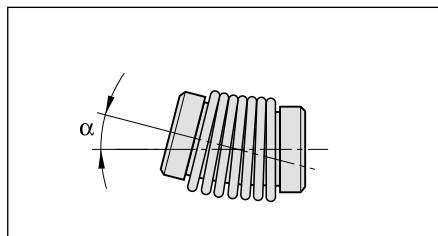
	for ROD 400 series
Hub bore	8/8 mm
Kinematic transfer error*	$\pm 20''$
Torsional rigidity	$225 \frac{\text{Nm}}{\text{rad}}$
Max. torque	0.98 Nm
Max. radial offset λ	≤ 0.2 mm
Max. angular error α	$\leq 1.5^\circ$
Max. axial motion δ	≤ 0.3 mm
Moment of inertia (approx.)	$2.5 \cdot 10^{-6} \text{ kgm}^2$
Permissible speed	20000 min^{-1}
Weight	30 g

*With radial misalignment $\lambda = 0.1$ mm,
angular error $\alpha = 0.15$ mm over 100 mm $\cong 0.09$, valid up to 50 °C

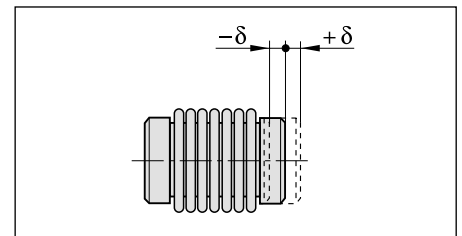
Radial offset



Angular error

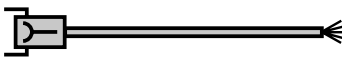


Axial motion



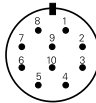
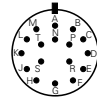

Connecting Elements and Cables

Connecting Cables

Cable diameter 6.5 mm		
Connector	Cable Specification	
10-pin	4x 2x 0.18 mm ²	736 060-01 (1m) 736 060-03 (3m) 736 060-05 (5m)
17-pin	4x 2x 0.18 mm ²	736 061-01 (1m) 736 061-03 (3m) 736 061-05 (5m)

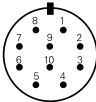
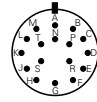

Pin Layout

□ TTL - C / □ HTL - C

10-pin RM15WTRZ-10P(71) flange socket				17-pin MS3102B-20-29P flange socket								
												
	Power supply			Incremental signals						Other signals		
10-pin RM15WTRZ-10P(71) flange socket	1	2	10	3	4	5	6	7	8	/	9	/
17-pin MS3102B-20-29P flange socket	H	K	T	A	N	C	R	B	P	M	/	D/E/F/G/J/L/S
	U_P	0V	FG	U_{a1}	\overline{U}_{a1}	U_{a2}	\overline{U}_{a2}	U_{a0}	\overline{U}_{a0}	0V	Vacant	Vacant
	White	Black		Red	Pink	Olive	Blue	Yellow	Orange			

Cable shield connected to housing; **U_P** = power supply

□ HTLs- C / Open Collectors

10-pin RM15WTRZ-10P(71) flange socket				17-pin MS3102B-20-29P flange socket								
												
	Power supply			Incremental signals						Other signals		
10-pin RM15WTRZ-10P(71) flange socket	1	2	10	3	4	5	6	7	8	/	9	/
17-pin MS3102B-20-29P flange socket	H	K	T	A	N	C	R	B	P	M	/	D/E/F/G/J/L/S
	U_P	0V	FG	U_{a1}	0V	U_{a2}	0V	U_{a0}	0V	0V	Vacant	Vacant
	White	Black		Red	Pink	Olive	Blue	Yellow	Orange			

Cable shield connected to housing; **U_P** = power supply

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